³ Diagnosis of planktonic trophic network ⁴ dynamics with sharp qualitative changes

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ABSTRACT

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19 Trophic interaction networks are notoriously difficult to understand and to diagnose (i.e., to 20 identify contrasted network functioning regimes). Such ecological networks have many direct 21 and indirect connections between species and these connections are not static, but often vary in 22 timeSuch ecological networks welcome numerous feedbacks between species and populations 23 and are not frozen at all, as soon as we observe them over a long enough term. These topological changes, as opposed to a dynamics on a static (frozen) network, may be triggered by natural 24 forcings (e.g., e.g., seasons) and/or by human influences (e.g., e.g., nutrient or pollution inputs). 25 26 Aquatic trophic networks are especially dynamics and versatile, thus supporting suggesting new 27 approaches for diagnosing identifying network structures and functioning dynamics in a comprehensive way. 28

30 In this study, we build a possibilistic qualitative model was builded for this purpose. Borrowing discrete-event models to from theoretical computer sciences, we developed a mechanistic and 31 32 qualitative model were developed allowing computing exhaustive dynamics of a given trophic network and its environment. Once the model definition is assumed, it provides all possible 33 pathways-trajectories of the trophic-network from a chosen initial state. In a rigorous and 34 35 analytical approach, for the first time, we validated the model on one theoretical and two observed trajectories recorded at freshwater stations in La Rochelle region (Western France). 36 37 The model appears easy to build and intuitive, and it-provideds otheradditional relevant 38 trajectories pathways to the expert community. We hope such mathematical formal approach 39 to open a new avenue in diagnosing_identifying_and predicting trophic (and non-trophic) 40 ecological networks. 41

42 *Keywords:* Interaction network; Freshwater ecosystem; Qualitative model; Discrete-Discrete-event 43 model, Plankton a mis en forme : Anglais (Royaume-Uni)

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IntroductionINTRODUCTION

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Trophic networks (TNs) form the backbone of ecosystem functioning, as they simultaneously condition food acquisition, prey and predator demography, individual and population behaviours, and phenotype selection, among other consequences (Lindeman 1942, Johnson 2000, Majdi et al. 2018). Trophic processes are responsible for most matter and energy fluxes within ecosystems, but the fates and properties of ecosystems are hardly predictable mainly due to the lack of knowledges (Mouquet et al. 2015). Trophic processes have been well studied in ecology, although mainly mostly considered as frozen in time, i.e., with a fixed (or static) topology and fixed signed relationshipsinteractions. This simplification may be due to data lacking data-over the long term and as well as to equation-based models dedicated to flux and abundance variations on a frozen network (e.g., e.g., Thébault and Fontaine 2010, Kéfi et al. 2015). In this study, we provided an original framework to handle trophic network<u>TN</u>s with sharply changing structures and to model their possible dynamics.

So far, trophic networkTNs are difficult to understand and to handle, in other words, hard to *diagnose* between constrasted functioning under changing environmental conditions. Any new functioning involves specific ecosystemic components and interactions, justifying why we will focus on qualitative functioning *regimes* rather than quantitative component abundances and interaction intensities. First of all addition, they_TNs_usually gather a large number of populations or species in an even larger number of trophic interactions. Hence, to understand trophic dynamics would require not only to model a large and realistic number of components, but also to be able to calibrate the weights (coefficients) of each component and each interaction involved (Ings et al. 2009, Wallach et al. 2017, Majdi et al. 2018). For this reason, most trophic models focus on wide categories of populations, with a-functional approachcategories, such as carnivores, herbivores and/or detritivores (e.g.-e.g., Thébault and Fontaine 2010), and approximate their trophic parameters. Even powerful models intending to bypass such limitations, such as qualitative models based on differential equation systems are limited in size (May 1973, Dambacher et al. 2003).

70 There is a-an even stronger limitation of trophic studies in ecology: they mostly assume a frozen network 71 of interaction (Thébault and Fontaine 2010, Kéfi et al. 2016). Not only is it harder to handle a-changing network 72 changing in topology (structure), but we have no idea on how such a network may change (typologically) in 73 time, and, thus, how to model it. Indeed, as soon as the study covers several generations of some of the species 74 involved in the network, some other species may invade and/or go extinct (Mooney and Hobbs 2001, Warren 75 et al. 2005). Hence, these events strongly modify the network structure and, in turn, the system dynamics. 76 Equation-based models are not well adapted to handle dynamical systems on dynamical structures (sometimes 77 called DS², Giavitto and Michel 2003), whereas some tools developed in theoretical computer sciences are 78 perfectly adapted to this task. In particular, discrete-event systems such as graph transformations or Petri nets 79 are able to handle sharply changing networks by formalizing the way components and interactions may appear 80 and disappear (König et al. 2018, Gaucherel and Pommereau 2019). While graph transformations are directly 81 adding/removing some nodes and edges, Petri nets are only mimicking such addition/removal by marking with 82 some tokens the presence/absence of the handled nodes and edges REFS. In this study, we developed will 83 provide a Petri net to model any trophic interaction network topological change, and will illustrate it on a 84 realistic planktonic trophic networkTN.

86 Planktonic trophic networkTN models are usually composed of fixed number of functional nodes that gather groups of individuals sharing the same ecological function. Mass fluxes (usually in carbon or nitrogen) 87 88 between nodes are predefined according to trophic linksinteractions. In a context of an emerging biological 89 oceanography discipline and regarding the limited computing resources, first planktonic TN (or food-web-food 90 web) models simply consisted in mass fluxes between nutrients, phytoplankton and zooplankton nodes (Steele 91 1958, 1974). These so-called NPZ models (NPZD, NPZDB or even NPZF when detritus, bacteria or fishes are 92 comprised, respectively) coupled to observed or simulated physical conditions demonstrate their predictive 93 ability to capture bulk system properties (biomass and primary production) at both regional and global scale 94 (Mitra et al. 2007, Kriest et al. 2010, Oke et al. 2013, Hernández-Carrasco et al. 2014, Turner et al. 2014, Kumar 95 and Kumari 2015).

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96 However, in order toTo better understand biogeochemical cycling (e.g., e.g., export fluxes, carbon 97 sequestration, organic matter recycling, microbial loop), planktonic food-web-TN should be delineated and 98 planktonic compartments in models could thus be refined into Planktonic Functional Types (PFTs). Plankton 99 groups are thus defined according to common ecological functions (e.g., e.g., nitrogen fixers, calcifiers and 100 silicifiers), sizes (e.g., e.g., picophytoplankton, nanophytoplankton, microphytoplankton) and/or key taxonomic 101 groups (e.g., cliatoms, flagellates) (Le Fouest et al. 2013, Villaescusa et al. 2016, Kerimoglu et al. 2017, 102 Petersen et al. 2017, Maar et al. 2018, Meddeb et al. 2019). However, refinements of planktonic food-web TN 103 models meets greatly complicate with model formulations formalization, parametrization and requires 104 morelack of data, which increases uncertainties with model outcomes and in fluxes between defined groups 105 (Anderson 2005).

107 To faceFacing gaps in ecological knowledge and lacks of data, inverse modelling intend to derives flows of 108 energy within trophic networkTNs from simple biomass estimates and rates measurements. Vézina and Platt 109 (1988) were the first to use it for inferring mass fluxes through a planktonic trophic networkTN in the English 110 Channel. Inverse modelling is therefore advantageous when dealing with underdetermined systems and 111 results into a space of possible solutions that fulfil a set of linear equalities and inequalities. A unique preferred 112 solution is then selected from optimization or statistical methods. While vital rates and biomass can be easily 113 measured for high trophic levels (e.g., e.g., fishes), their quantification for low trophic levels (e.g., bacteria, 114 autotroph plankton) remains uncertain and questions the robustness of inverse modelling for planktonic 115 compartments study (Vernet et al. 2017, Saint-Béat et al. 2018). Overall, biological constants (production, 116 consumption, assimilation), biomass and ecological interactions are therefore not easy to measure in planktonic food-websTNs, resulting into an over-simplification of planktonic food-web-TN models (Anderson 117 118 2005, Flynn 2006). For all these reasons, our main objective in this study consists in developing a model able 119 to identify (to diagnose) any qualitative functioning regimes of the same TN under changing environmental 120 conditions.

123 We addressed here the leading question: what are all the possible trajectories (pathways) of such an 124 aquatic TN? A trajectory is defined here as a sequence of TN states (regimes) and transitions in time, possibly 125 exhibiting bifurcations and not necessarily being quantitative. More precisely, we question the various 126 qualitative regimes this network can reach from winter to summer environmental conditions. As a second sub-127 question, we wonder whether a detailed model could exhibit new or counter-intuitive TN trajectories. To 128 address these issues, we propose here to develop a qualitative and discrete model providing all possible 129 trajectories (or pathways) of the trophic network under study, in order to keep a rigorous (mathematical) 130 control on the model. This assumption allowsWe assume here that the system to become finitemay be 131 qualified and tothus exhibit a finite number of states, automatically computed and gathered into a so-132 calledPetri net state space (Pommereau 2010, Reisig 2013). Then, a detailed and automatic analysis of this 133 state space exhaustively provides the possible fates (e.g., trajectories, stabilities, collapses, if any) of the 134 studied system. We chose to illustrate this original method on a well-studied plankton trophic networkTN in 135 wetlands, freshwater marshes of Charente Maritime region (Western France, Tortajada et al. 2011). Such a 136 system is well instrumented (measured) and will provide an expected theoretical trajectory of changing trophic 137 networkIN, as well as two observed trajectories at different stations (Masclaux et al. 2014). The succession of 138 planktonic trophic networkIN and the different regimes of the planktonic trophic networkIN are well known 139 according to the season (Masclaux et al. 2014). We will develop the corresponding Petri net of this system and 140 then validate it, for the first time, on theoretical and observed trajectories. We will finally discuss the power 141 and drawbacks of such discrete and qualitative models for trophic ecology.

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MATERIALS AND METHODS Methods

143 Aquatic trophic networks

144The Charente-Maritime marshes of the French Atlantic coast (Fig. 1) are the second largest French wetland145zone (over 100,000 hectareskm²). The type of freshwater marshes is the unreplenished drained marshes which146constitute a significant artificial hydrographic network of channels and ditches. To mitigate and prevent drying147of marshes, locks control the channels and ditches (for more details, see Masclaux et al. 2014). Samples of the

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planktonic TN were recorded at two stations (stations A and B) at successive dates (eight weeks during winter and spring 20132) to reconstruct the network trajectories and their environment along time (Masclaux et al. 2014). All the details were in the paper of Masclaux et al. (2014). Briefly, the water parameters studying were temperature, nutrients (nitrates...), Dissolved Organic Matter (DOC) concentration, biomass and production of bacteria, biomass and primary production of phytoplankton by size class (microphytoplankton for > 20 µm; nanophytoplankton for 3-20 µm and picophytoplankton for < 3µm), bacterial biomass, protozoa biomass, metazoan microzooplankton and mesozooplankton biomass. Differents flux between preys and predators were measured: Micro- and mesozooplankton grazing rates on the three phytoplankton size classes as well as mesozooplankton grazing rates on protozoa (Masclaux et al. (2014). The TN regimes were determined with an hierarchical ascendancy classification (HAC, Euclidean distance and Ward method). The observed trajectories of the system were made with data recorded at two stations (stations A and B). The planktonic trophic networkTN regime changed during the transition from winter to springsummerspring transition, from biological winters, after thatfollowed by herbivorous trophic networkTNs, to finally reach trophic networkTNs qualified as multivorous and distinguishing three levels of multivory (weak multivorous, multivorous and strong multivorous) (Masclaux et al. 2014). (for more details, see Masclaux et al. 2014).

Figure 1 - Location of the study site and of the two sampled stations (A and B, inset) along the Atlantic

The model was built with several categories of variables (Fig. 2): Phytoplankton, Zooplankton, Resources,

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16	7 <u>Microbes and Abiotic components characterizing the environment. The main functional groups were: 1)</u>		
16	8 phytoplankton by size class (microphytoplankton for > 20 μm: <i>MicroP</i> ; nanophytoplankton for 3-20 μm: <i>NanoP</i>		
16	9 and picophytoplankton for < 3µm: <i>PicoP</i>) all in green (Fig. 2); 2) metazoan microzooplankton (<i>MicroZ</i>) and		a mis en forme : I
17	0 mesozooplankton (<i>MesoZ</i>) in red; 3) resources as nitrates (<i>Nit</i>) and Dissolved Organic Matter (<i>DOC</i>) in brown;		<u> </u>
17	1 4) microbes such as bacteria (Bact) and protozoa (Proto) in blue; and 5) abiotic variables in grey with the		a mis en forme : I
17	2 component <i>envir</i> , which corresponds to the temperature and light conditions and <i>renew</i> which corresponds		a mis en forme : I
17	3 to the possible renewal of water (i.e., flush) in the marshes depending on the rainfall and water usages		a mis en forme : I
17	4 (agriculture, breeding). In the model, the environmental conditions were summarized by a component envir,	//	a mis en forme : I
17	5 which corresponds to the conditions of temperature and light, a component <i>nit</i> corresponding to the presence		a mis en forme : I
17	6 or absence of nitrates, and <i>renew</i> corresponding to the possible renewal of water (i.e. flush) in the marshes		
17	7 depending on the rainfall and water usages (agriculture, breeding). The main functional groups of plankton		a mis en forme : I
17	8 were: 1) phytoplankton by size class (microphytoplankton for > 20 μm: <i>MicroP</i> ; nanophytoplankton for 3-20		a mis en forme : I
17	9 µm: NanoP and picophytoplankton for < 3µm: PicoP), 2) different grazers as protozoa (Proto), metazoan		a mis en forme : I
18	0 microzooplankton (MicroZ) and mesozooplankton (MesoZ), and 3) bacteria, which uses dissolved organic		a mis en forme : F
18	1 matter (DOC) (Fig. 2). In more details, the planktonic trophic networkTN and all the possible fluxes	1000	a mis en forme : F
18	2 (interactions) between components concerns grazing fluxes with some preferential predation, and potential	1////	
18	3 competitions between organisms (Fig. 2). Protozoa graze on bacteria, <i>PicoP</i> and <i>NanoP</i> and are grazed by		a mis en forme : I
18	4 MicroZ and MesoZ. MicroZ graze on bacteria, PicoP, NanoP and Proto. MicroP is grazed principally by MesoZ,		Commenté [g4]: A
18	5 which used <i>MicroZ</i> , <i>NanoP</i> and <i>Proto</i> as preys. Three Two preferential fluxes interactions are forcing the model:		à vérifier entre Env
18	6 i) competition between bacteria and <i>PicoP</i> suggesting that each may survive and be detrimental for the second		(normal ?)
18	7 one, ii) preferential grazing of MicroP by MesoZ and preferential grazing of NanoP by MicroZ. In brief, The	////	Commenté [CD5]
18	8 ascendantplain upward arrowsedges correspond to relation prey-predator interactions, the descendantwhile	(1))	a mis en forme : F
18	9 <u>dashed downward</u> arrows<u>edges</u> are the matter in form of<u>resulting</u> detritus (<u>toward DOC</u>	$\mathbb{N}(1)$	a mis en forme : H
19	0 <u>variable</u> compartment).	/////	a mis en forme : H
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coast of France.

Figure 2 - The detailed interaction network used in this study. The trophic network-and non-trophic components are displayed as nodes of various colors (Phytoplankton: green, Zooplankton: red, Resources: brown, Microbes: blueleu and Abiotic components characterizing the environment: greyred: n, green: phytoplankton, brown: resources, blue: microbes and grey: abiotic components).

Predation interactions are displayed as plain (upward for trophic) and dashed (downward for degradation) edges, with preferred prey populations highlighted with red_doted-dashed blue-edges.

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198 Petri Nets and a simplistic Prey-Predator model

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199 We first summarize the successive steps required to build any ecosystem Petri net and will then illustrate 200 these steps with a toy-model. Our generic approach to model ecosystems has been called the EDEN (Ecological 201 Discrete-Event Network) modeling framework and is here specifically applied to an aquatic trophic TN. Any 202 203 ecosystem Petri net is developed in three successive steps (Fig. 3): i) an intuitive graph (i.e., i.e., a set of components nodes and edgestheir related processes) is built to represent the studied ecosystem with its 204 components and their related processes, focusingbased on the leading question addressed by the model (Fig. 205 3a); ii) we transform this ecosystemic graph, now called the interaction network, is then transformed into a 206 formal model based on a discrete-event Petri net and its associated rules (as explained in the next paragraph, 207 Fig. 3b); iii) each rule is finally normalized to make it simpler and unambiguous for allowing a rigorous handling 208 of the network changes. Then, the Petri net is run (computed, Fig. 3c) and analyzed (Fig. 3d) to determine the 209 whole range of the ecosystem dynamics. However, the Petri net (steps i and ii) is hidden to the (ecologist) user 210 and is automatically built (in Python language, see Suppl. Mat.) once the ecosystem graphcomponents and 210 211 212 processes have been chosen has been defined by the ecologists.- We first illustrate here the functioning of the model using a simplistic prey-predator system (Fig. 3a). Additional technical details on the principle and uses 213 of Petri nets, in particular the way they are computed, can be found in the literature (Pommereau 2010, Reisig 214 2013, Gaucherel and Pommereau 2019).

216 We illustrated here the basic functioning of the model using a simplistic prey-predator system (Fig. 3). Any 217 218 ecosystem network can be represented as a multi-digraph (i.e. a directed graph (with parallel edges). In this graph, every material component of the ecosystem (e.g., e.g., abiotic: temperature; biotic: a population; 219 anthropogenic: nitrate inputs) is represented by a node (or variable), with two Boolean states: "present" (the 220 221 component is functionally present in the system, or above a chosen threshold, also denoted "+") and "absent" (functionally absent of the system, or below the same threshold, ornoted "-"). In the prey-predator 222 exampletoy-model, only two nodes are defined: the prey and the predator populations. Any state of the 223 224 ecosystem is defined by the set of "+" and "-" nodes (Fig. $\frac{3b_{3b}}{3b}$), and "±" in tables of this paper, when they may oscillate between successive states. The maximal number of possible system states is 2#nodes and grows 225 exponentially with the node number. The state of a node depends on the nodes to which it is connected, while 226 a connection between nodes is assumed as soon as one process explicitly connects the different components 227 (Fig. 3b3a-b). The rules correspond to any physicochemical, and/or bio-ecological and/or possibly socio-228 economic processes (e.g., e.g., if the prey population is neglectable below a chosen threshold (-), the predator 229 population becomes below its associated thresholdneglectable too), and thus represent all possible 230 interactions between nodes-components composing the studied ecosystem-studied. In the prey-predator 231 system, two rules only are defined: R1, the predation itself: the predator eats the prey, and R2, the mortality: 232 without prey, the predator dies (Fig. 3a and 3c). In the Petri net language, nodes are called places and rules 233 are called transitions, both being connected through (oriented) arcs (Fig. 3b3b).

Figure 3 - Illustration of a simplistic prey-predator system (a), with its associated Petri net (b), its qualitative dynamics (c), and the <u>computed</u> marking graph also called state space (d). The system is made up of two components, the prey (N) and predator (P) populations, and two interactions connecting them (rules R1 and R2), [as seen on the automaton (a)]. The corresponding Petri net is made up of four places (P+, P-, N+, N-) and two transitions R1 and R2, <u>where linked by</u> unlabeled and unweighted arcs (b). Starting with the presence of both populations, it is possible to list all system states encountered [d₁, d₂, d₃] (c), and to connect them with the rules (absent nodes and inactivated rules are displayed in grey). The net is depicted in the initial state (c), and the successive states may be deduced from the token (black dot in [a)], eirculation seen in the dynamicsmovements between places (b). The marking graph of the Petri net (d) is depicted with each state number (S0, S1, S2)[d₀, d₁, d₂) referring to the dynamics described above (b). Notice that a specific state of the system [d₄] (S3) may not be reached from this initial condition and with these rules (d).

247 Discrete and qualitative dynamics

A separate rule describesAny rule of such discrete-event models combines the left-hand condition and a right-hand condition parts as: "transition's name: condition >> realization". For a rule to be applied, the state of the node (variable) must satisfy its application condition; the rule is then said "enabled". If so, the application

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a mis en forme : Police :Italique a mis en forme : Police :Italique 251 of the rule modifies the state of the nodes as stipulated in its realization part; the rule is then fired (i.e. 252 253 executed or applied). In the prey-predator system (Fig. 3), the rules are written as R1: P+, N+ >> N- and R2: , P+ >> P-. Since the rules modify node states, they change the overall system state (i.e., i.e., the state of the state o 254 system aggregates all node states). Therefore, the entire system shifts from one state to another one through 255 the successive applications of enabled rules (Fig. 3c). The computation of the defined Petri net produces the 256 state space, which provides the set of all system states reachable by the rules defined (Fig. 3d). As a corollar 257 the system states are connected to each other by some of these rules in the state space too. The size of the 258 state space is usually much smaller than the number of possible system states (2", with n the number 259 components or nodes/variables), because the computation starts from a specific initial condition and becaus 260 rules have specific application conditions. We Following the computer science community, we developed son 261 tools to automatically divide large state spaces into *merged* (simplified) state spaces, as explained in the ne 262 sub-section. 263

Firing a rule independently to some others often leads to unrealistic trajectories (e.g., e.g., removi 264 265 flushing water without removing fishes-plankton in it). Therefore, we defined new objects called constrain 266 preventing the model from simulating such unrealistic (socio-ecological)-trajectories. Constraints have 267 268 condition and a realisation part, just as rules stricto sensu do, and model inevitable (mandatory) even transitions given the system state. The sole difference between rules and constraints is that constraints ha 269 priority on rules stricto sensu. In the prey-predator system, the system state $S1_{d_1} = \{\{N, P^+\}\}$ is unrealistic 270 so, the rule R2 has to be transformed into a constraint (C1: N-, P+ >> P-). From a given state, the model fi 271 simulates all trajectories opened up by the defined constraints and then only, when all the system stat 272 obtained are realistic (i.e., there is no longer any enabled constraint), the enabled rules are fired (Fig. 3c 273 274 Notice that the modelled system may stay an indefinite time in any of the computed states, as no rule force it to leave the qualitative state (i.e., the system may experience quantitative dynamics yet without sha 275 qualitative changes). In brief, the discrete model proposed here is qualitative, mechanistic (processes a 276 explicit), non-deterministic (no stochasticity yet several possible outcomes from each state) and asynchronou 277 (i.e., all rules are applied as soon as possible, no rule conflict) (Reisig 2013, Gaucherel and Pommereau 2019 278 The EDEN models are also causal and chronological vet non-temporized, i.e., transitions and time steps are n 279 guantified (and not probabilized).

281 Methodology and TN trajectories and validation methodology

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282 The theoretical plankton trophic networkIN modeled here combines nine different nodescomponent 283 associated to the dominant functional groups possibly present in the channel freshwater marshes, and tw 284 285 additional components nodes featuring environmental conditions (Table 1, Fig. 2). To link-connect them, w defined 34 processes and seven constraints encompassing at least four trophic levels (Table 2, Fig. 2). 286 validate the TN model, oneA theoretical trajectory (T1) has been was defined and two observed trajectori 287 (T2-3) were recorded the studied system at two distant stations (Table 3 Supplementary Materials, Table SM 288 2). For the model to be validated, we expect As a validation stage, we intend not only to detect these successi 289 states (e.g., {S0, S1, S2, S3}) in the modeled state space, but also to detect them in the correct succession 290 orders. The model always starts in winter conditions or with a flush in summer conditions, with the nor 291 Renew present only, which brings back some source of inorganic nitrogen in the system (Table 1). To su 292 whether the model was able to recover the expected trophic regimes, weWe tested two variants of the model 293 i) the full model intending to grasp the TN functioning and, ii) the samea similar model (called seasonal) y 294 without return in winter conditions (R3, called the "seasonal model"0, Table 2), thus getting the model stu 295 in summer conditions. The model starts in winter conditions or with a flush in summer conditions, with the 296 node Renew present only, which brings back some source of inorganic nitrogen in the system (Table 1). 297

For the full and seasonaleach models, we will compute the state space and the *merged* state space, and will check whether <u>observed</u> trajectories T1 to T3 are correctly recovered. A merged state space is a simplified state space gahering under the same nodes the sets of mutually reachable states of the modelled system, a topological structure called a *structural stability*. Such structure is interpreted as a stable regime as, by definition, any state in this stability may be reached by any other state belonging to it. Other stabilities may be automatically identified, such as *terminal stabilities*, from which the system can no more exit, *basins* gahering

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304	states having the same following states, and <i>deadlocks</i> , which are single states from which the system can no	
305	more exit. Merged states spaces are much more compact than full state spaces, and summarized trajectories	
306	are easily revealed.	

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Table 1 - The plankton model_IN components and their associated modeled nodes-variablesin the TN interaction network, with their abbreviations; and descriptions. Whether these ecological components are present (+) or absent (-) in the initial state is also displayed (second column).

Acronym	In initial state	Description	
Bact	-	Bacteria	
PicoP	-	Picophytoplankton	
NanoP	-	Nanophytoplankton	
MicrP	-	Microphytoplankton	
Proto	-	Protozoa	
MicrZ	-	Microzooplankton (metazoa)	
MesoZ	-	Mesozooplankton	
DOC	-	Dissolved organic matter	
Nit	-	Nitrates, linked to seasons or flush	
Envir	-	Environmental and climate conditions	
Renew	+	Water and Nitrate inputs (rain or humans)	

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ctory, theoretical and observed regimes re listed in columns and present (+)/absent () component rkTN are listed in c The displayed in Fig. 5a

THEORY	Stage 1	Stage 2	Stage 3	Stage 4	Stage 5	Stage 6
Bact	-	-	-	+	+	+
PicoP	-	-	-	+	+	+
NanoP	-	+	+	+	-	-
MicrP	-	+	+	-	-	-
Proto	-	_	_	+	+	-
MicrZ	_	_	+	+	+	-
MesoZ	_	_	+	+	_	-
Nit	+	+	+	_	_	-
DOC	_	_	+	+	+	+
Envir	-	+	+	+	+	+
Renew	+	+	-	-	-	-
Regimes	Biological	Low	Herbivorous	Multivorous / Strong	Microbial	Microbial
(Fig. 5)	winter	herbivorous TN	TN	multivorous TN	TN	loop

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Commenté [g7]: EN FAIT, j'enlèverais cette table, qui me semble redondante avec la première des Supp. Mat. (elle est plus détaillée, mais n'apporte que de la confusion selon moi). D'ailleurs, elle était mal numérotée. A discuter... **Commenté [CD8R7]:** C'est la théorie et cela décrit un peu plus les réseaux trouvés à la figure 5, non ? Je le garderais. a mis en forme : Barré a mis en forme : Barré

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318 State spaces and computed dynamics

319 |320 The full model provides a state space made up of 765 states gathered into a unique dynamical structure (a so-called structural stability, Fig. SM1aa-Suppl.). This structure was interpreted as a stable and highly resilient

Results RESULTS

321 dynamics as, by definition, any state in this stability may be reach by any other state belonging to it. Yet, when 322 rule zero (RO, seasonal oscillation) is deactivated, tThe seasonal model gets stuck into a high number (12, plus 323 two basins) of successive structural stabilities of various sizes (Fig. <u>4 and SM</u>1b-Suppl.). When oriented 324 downward in time (i.e., following causality and chronology), the whole system inexorably inevitably converges 325 toward a small terminal stability (made up of four states) in which the system appearsis in a biological winter 326 (i.e., i.e., few living species, in green, Fig. SM1b-Suppl.). Some of the reached stabilities exhibit a large number 327 of states and may keep the system into such specific stabilities during indefinite time (in purple, Fig. 4 and 328 SM1b-Suppl-). In brief, the seasonal model displays the same state space than the full model, but with a 329 possible return to the initial biological winter regime thus connecting the bottom states (in red, Fig. 4a) to the 330 top states (in pink, Fig. 4a). This is why we observe a single cycling stability in the full model state space (Fig. 331 SM1a). We call such structural stabilities TN "regimes", i.e. a set of interconnected states displaying a coherent 332 TN behaviour.

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Table 3 - Rules and constraints used in both full and seasonal models, with their formal expression (first column) and descriptions (second column). Only the rule N°O (in italic and bold) is discarded in the seasonal version of the model.

CONSTRAINTS	Descriptions
DOC- >> Bact-	C1 Without organic matter (DOC), Bacteria disappear
	C2 Without Nitrates, all kinds of phytoplankton except
Nit- >> NanoP-, MicrP-, DOC+	Pico disappear (and produce organic matter)
	C3 Without all its preys (but Bacteria), Protozoa disappear
Bact+, PicoP-, NanoP- >> Proto-, DOC+	(and produce organic matter)
Bact-, Proto-, PicoP-, NanoP- >> MicrZ-,	C4 Without all its preys (but Bacteria), Microzooplankton
DOC+	disappear (and produces organic matter)
Proto-, MicrZ-, NanoP-, MicrP- >>	C5 Without all its preys, Mesozooplankton disappear (and
MesoZ-, DOC+	produces organic matter)
	C6 In winter, all Phytoplankton disappear (and do not
Envir- >> PicoP-, NanoP-, MicrP-	produce organic matter)
PicoP+, NanoP+, MicrP+ >> Nit-	C7 With all Phytoplankton (present), Nitrates disappear
, ,	and the second
RULES	
Envir+ >> Envir-, Renew+	R0 After summer (and spring) comes winter
Envir- >> Envir+	R1 After winter comes summer (and spring), with a bloom
	R2 Nitrate input is due to water flush from human
Envir+, Renew+ >> Nit+, Renew-	management or rainfall
Envir-, Renew+ >> Nit+, DOC-, Bact-,	

Envir-, Renew+ >> Nit+, DOC-,	Bact-,
Proto-, PicoP-, NanoP-, MicrP-	, MicrZ-, R3 In winter, the Reset of the system is due to water flush
MesoZ-	from rainfall (but there is a Nitrate inputs)
Envir-, Renew+ >> Renew-	R4 In winter, we stop the flush after its action (reset)
DOC+ >> Bact+	R5 Bacteria use organic matter, without removing it
Bact+, DOC+ >> DOC-	R6 Bacteria use organic matter and remove it
	R7 Microphytoplankton and Nanophytoplankton use
Envir+, Nit+ >> MicrP+, NanoP	 Nitrates in summer, without removing them
	R8 Picophytoplankton use Nitrates, without removing
Envir+, Nit+ >> PicoP+	them
Bact+ >> Proto+	R9 Protozoa graze on Bacteria, without removing them
	R10 Protozoa graze on Bacteria, which disappear and
Bact+, Proto+ >> Bact-, DOC+	produce organic matter
	R11 Protozoa graze on Picophytoplankton, without
PicoP+ >> Proto+	removing it
	R12 Protozoa graze on Picophytoplankton, which
PicoP+, Proto+ >> PicoP-, DOC	 disappears and produce organic matter

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	R13 Protozoa graze on Nanophytoplankton, without
NanoP+ >> Proto+	removing it
	R14 Protozoa graze on Nanophytoplankton, which
NanoP+, Proto+ >> NanoP-, DOC+	disappears and produce organic matter
	R15 Mesozooplankton graze on Microphytoplankton (its
MicrP+ >> MesoZ+	PREFERED prey), without removing it
	R16 Mesozooplankton graze on Microphytoplankton,
MicrP+, MesoZ+ >> MicrP-, DOC+	which disappears and produces organic matter
	R17 Mesozooplankton graze on Nanophytoplankton,
MicrP-, NanoP+ >> MesoZ+	without removing it
	R18 Mesozooplankton graze on Nanophytoplankton
MicrP-, NanoP+, MesoZ+ >> NanoP-,	(secondary preferential prey), which disappears and
DOC+	produces organic matter
	R19 Mesozooplankton graze on Protozoa, without
MicrP-, Proto+ >> MesoZ+	removing them
MicrP-, Proto+, MesoZ+ >> Proto-,	R20 Mesozooplankton graze on Protozoa, which
DOC+	disappears and produces organic matter
	R21 Microzooplankton graze on Nanophytoplankton (its
NanoP+ >> MicrZ+	PREFERED prey), without removing it
	R22 Microzooplankton graze on Nanophytoplankton,
NanoP+, MicrZ+ >> NanoP-, DOC+	which disappear and produce organic matter
	R23 Microzooplankton graze on Picophytoplankton
NanoP-, PicoP+ >> MicrZ+	(secondary preferential prey), without removing it
NanoP-, PicoP+, MicrZ+ >> PicoP-,	R24 Microzooplankton graze on Picophytoplankton, which
DOC+	disappear and produce organic matter
	R25 Microzooplankton graze on Protozoa, without
NanoP-, Proto+ >> MicrZ+	removing them
NanoP-, Proto+, MicrZ+ >> Proto-,	R26 Microzooplankton graze on Protozoa, which
DOC+	disappear and produce organic matter
	R27 Microzooplankton graze on Bacteria, without
NanoP-, Bact+ >> MicrZ+	removing them
	R28 Microzooplankton graze on Bacteria, which disappear
NanoP-, Bact+, MicrZ+ >> Bact-, DOC+	and produce organic matter
	R29 Mesozooplankton graze on Microzooplankton,
MicrZ+ >> MesoZ+	without removing it
	R30 Mesozooplankton graze on Microzooplankton, which
MicrZ+, MesoZ+ >> MicrZ-, DOC+	disappears and produces organic matter

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337 Four <u>TN</u> regimes were revealed by the <u>full and seasonal</u> models (Fig. 4<u>a</u> and Table <u>SM1-Suppl.</u>): <u>the SO</u>} 338 339 biological winter regimes, without planktonic bloom, with oscillations of both zooplankton feeding on bacteria and organic matter; the s1)-a regime in which all components are present because the environment is 340 favourable to the development of organisms with many fluctuations of them; the S2} a-multivorous TN regime 341 |342 with a mix of preys and various predators such as protozoa and both zooplankton (MicrZ and MesoZ), and finally, the S3) - a regime centred on protozoa and mesozooplankton with a few preys but the oscillation of 343 Bacteria (Fig. 4a, Table SM1-Suppl.). The trajectories passing through different regimes were diverse and 344 depend on the rules fired from the initial state (Fig. 4b): either the TN system shifts between various types of 345 S0 regimes, or it crosses successively regimes S0 to S1, S2, S3 (with possible ways back) and then back to S0. 346

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348 349 350 351 352 Figure 4 - The merged state spaces of the seasonal model (a, as in Fig. SM1a-Suppl.), on which each node corresponds to a structural stability (i.e. i.e., a set of TNmtually reachable states), and each edge corresponds to specific-irreversible transitions between two-successive stabilities. Here, structural stabilities are labeled with system components that are systematically present (+) in their associated states (see Fig. SM2). To see components that are systeamtically absent in stabilities). This figure helps $identifying the various regimes (b, \underline{and} Table \underline{SM} 1 \underline{Suppl.}) reached by the \underline{trophic network} \underline{TN} system along$ to the (downward) trajectories computed.

355 Model validation

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356 All states of the theoretical trajectory are correctly recovered predicted by the model and, as the model 357 exhibited a single stability, the system is certain to successively reach all these states (although we do not know 358 by which complex complicated trajectories, Fig. 4a, Table SM1-Suppl.). This observation definitely validates the 359 model. The theoretical planktonic TN trajectory (Table 2 and Fig. 5a) started by an (immature) regime, here 360 found duringnamed a the biological winter. They It then evolved toward low herbivorous TN, herbivorous TN 361 and variable multivorous TN (from weak to strong multivorous regimes, with protozoa, microzooplankton or 362 mesozooplankton, respectively), and microbial TN regime, and to finally reach a microbial loop regime. When 363 water in the marshes is renewed (Renew+), the TN returned to an immature biological winter regime, as may 364 the herbivorous and biological winter regimes too. All these TN regimes are recovered by the model (Fig. 5a), 365 yet with slightly different stabilities. The figure 5 is not intending to demonstrate this validation stage (already 366 done by identifying the successive trajectory states), rather than showing that all predicted states (coloured 367 nodes) are correctly recovered into the computed state space, and indeed connected through successive 368 transitions (bold edges). Note that this modeled trajectory is crossing many other intermediate states (Fig. 5a) 369 not found in the observations of (Masclaux et al. 2014). When In the seasonal oscillation model (rule R0) is 370 deactivated), the theoretical trajectory is predicted too (colored states, Fig. 5a), yet in a reverse order for with 371 the last two states (blue states at the bottom): in the reverse order, as the fourth multivorous regime may 372 directly reach the last depleted one.

374 The data of recorder at stations A and B, and associated to observed trajectories were correctly recovered 375 too. At station A, three regimes succeed along time, from A1 to A3 (Table SM2-Suppl-, Fig. 5b). The TN started by biological winter during four weeks with presence of nitrates and organic matter, but did not reach 376 377 favourable conditions for biological development. Then, the favourable conditions at week 5-five allowed the 378 development of phytoplankton (micro- and pico-plankton), and thus their zooplankton predators with 379 bacteria. This situation was typical of situations between herbivorous and multivorous TNs. Then, a 380 multivorous regime of TN settled until the week <u>8eight</u>. At station B, the observed succession displayed four 381 regimes, from B1 to B4 (Table SM2-Suppl-, Fig. 5c). The TN started by biological winter during three weeks and 382 favourable conditions arrived-occuring at week 4-four which allowed a presence of multivorous TN ("weak 383 multivorous TN" according to (Masclaux et al. 2014)) and at week 5-five an herbivorous TN. Then, a multivorous 384 regime of TN settled from week 6-six to week 8eight.

386	Figure 5 - The full (not merged) seasonal state space highlighting the three trajectories used in this study
387	(Table 2), namely the theoretical (a), station A (b) and station B (c) ones (Table 2 Suppl.). Here, each node
388	corresponds to a trophic networkTN state, connected to each other by downward transitions. The specific
389	states building the three trajectories are highlighted by node colors other than red and identifiers
390	corresponding to their numbers (last lines of trajectories in Table 2) and by bold edges.

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DiscussionDISCUSSION

The discrete-discrete-event and qualitative model of trophic network (TN) presented here is computed almost-instantaneously (< 0.01s) and provided, once the model is defined and assumed, all possible trajectories of this system (Fig. 4). Such approaches are called possibilistic (i.e. non-deterministic and nonprobabilistic) and appear relevant for most ecological studies. To our knowledge, it is the first attempt to model exhaustively a detailed <u>TN</u> (11 components, Table 1) and to accurately validate its qualitative dynamics) trophic network (but see Baldan et al. 2015, Gaucherel and Pommereau 2019), and to accurately validate its qualitative dynamics.

399 Complex dynamics of aquatic trophic networks

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400 In the Charente-Maritime trophic system, we discovered that this trophic systemTN may have followed 401 other trajectories than the one identified by experts in the theoretical model and in the ones observed (Fig. 402 5 and Supplementary Materials tables). First, the station B proves that DOC may be present in winter, thus 403 with the trophic networkIN fluctuating in intermediary states before reaching the usual trajectory 404 observed in Masclaux et al. (2014). Indeed, DOC in winter could be an allochthonous input from terrestrial 405 environment (Del Gorgio and Davis 2003). After winter (i.e. i.e., when Renew+ and Envir+ were present, 406 Table 1), all the modeled trajectories and all the TN regimes appeared at reach. The TN may come back to 407 immature-biological winter system states due to the nitrate inputs (Nit+, with R2) and to anthropogenic 408 activities (Tortajada et al. 2011). This situation happens when the water renewal is important and no 409 planktonic biomass accumulation is possible (David et al. 2020). Also, rainfall could happen and favour 410 nitrate leaching (R3), then pushing back the planktonic trophic networkIN to immature biological winter 411 system states. The model confirmed the key role of organic matter (DOC), as the system trajectories 412 differed when organic matter was present or absent at the beginning of winter. 413

414 From the initial state of the TN, the trajectories could be passing through slightly different biological 415 winter regimes (Fig. 4a-b) with oscillations of organic matter, bacteria, micro- and meso-zooplankton. 416 Similarly, Masclaux et al. (2014) found two types of Biological winter regimes, mainly depending on the 417 presence or absence of bacteria, and on some prevs and predators combinations. The model correctly 418 recovered different states of biological winters. The regime of multivorous TN was well recovered by the 419 model too (Masclaux et al. 2014). The multivorous TN is known to be highly stable (Legendre and 420 Rassoulzadegan 1995). However, the microbial loop, which has a transient nature (Legendre and 421 Rassoulzadegan 1995) did not appeared as a structural stability in the model either. 422

423 The regime gathering protozoa and mesozooplankton (Proto/MesoZ cycles) characterized by the 424 presence of predators with a few preys but the oscillation of bacteria was not found in the observations 425 (Masclaux et al. 2014). The modeled trajectory is crossing many intermediate states (Fig. 5a-c) not sampled 426 in the field. The field sampling frequency or the structural characteristics of the sampled wetlands likely 427 did not allow capturing all the possible states of TN: this reveals the ability of the model for exploring many 428 other possible states of the planktonic TNs and other trajectories of TN. In particular, the predicted 429 Proto/MesoZ regime has not yet been identified at the Charente Maritime sites, but work in progress at 430 other Atlantic arc territories has identified related TNs (F.-X. Robin ROBIN, pers. Comm.). Finally, bacteria 431 were frequently present in the ecosystem, and occupied a large place in the model (Table SM1-2-Suppl., 432 Table 2, Table 2 Suppl.). Bacteria seemed to frequently oscillate (Fig. 4a), although not visible in the merged 433 state space (i.e., bacteria frequently appear and disappear within structural stabilities). The model 434 confirmed that bacteria are frequently grazed by their grazers, as small protists are (Pernthaler 2005, Šimek 435 et al. 2013). Indeed, we know the strong control of bacteria by the protozoa in freshwater ecosystems.

436 Power and drawbacks of discrete-discrete-event models

An increasing number of trophic networkIN models are being developed today (Mitra et al. 2007, Kriest
 et al. 2010, Thébault and Fontaine 2010, Turnet et al. 2014, Kéfi et al. 2016, Hansen and Visser 2016,
 Kloosterman et al. 2016). But they still have three main limitations: a limited size and complexity, and a
 frozen (static) network with frozen (i.e., topology) interactions. In this study, we proposed an original

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441 model family (called the EDEN framework (Gaucherel and Pommereau 2019, Cosme et al. 2022)) to bypass 442 these limitations. It is based on a discrete-event system, well-known by computer scientists and more 443 recently by some molecular biologists (Thomas and Kaufman 2001, Reisig 2013). The price to pay by using 444 our qualitative model is that no more-quantitative and detailed dynamics is available; but in turn, no 445 difficult parameterization and construction is are required. Consequently, such approach is fully 446 complementary to already existing models in (trophic) ecology. Here, we provide for the first time to our 447 knowledge a discrete and qualitative model of TN to bypass such limitations. By the way, in the continuity 448 to previous theoretical attempts (May 1973, Dambacher et al. 2003), we open here new avenue for using 449 such original <u>qualitative</u> models in (ecosystem and trophic) ecology. The foundations of this proposition, 450 yet out of the scope here, are based on a theoretical ground assuming that ecosystems are informational 451 systems made up of material components and immaterial processes (Gaucherel 2019) represented in 452 summarized into theirthe interaction networks. 453

454 Such a model is intuitive, easy to build, tractable and rigorous (i.e., i.e., no trajectories have been 455 forgotten or added according to the mathematical Petri net engine). In addition, we said that it does not 456 require any detailed and quantitative calibration, as no parameter is required. The central assumption of 457 this approach is that it is possible to summarize ecological processes into qualitative rules, possibly 458 interpreted as long term and discrete discrete events. Other studies show that this approach is not limited 459 to trophic processes and may be applied to a high diversity of social-ecosystems (Gaucherel and 460 Pommereau 2019, Mao et al. 2021). In this study, we were lucky enough to collate several theoretical and 461 observed trajectories on-with which to validate the model, thus confirming that it is conform and accurate 462 (Fig. 5). Another quality of this type of models is to be heuristic, to force scientists questioning the 463 knowledge they have on the studied system and to collate it into a single coherent framework.

465 As perspectives, it appears at hand to model many TN stressors such as pollution, cleaning, drought, 466 invasive species and/or climate changes (Mooney and Hobbs 2001, Mouquet et al. 2015). Any complexification of the studied social-ecosystem is also possible, in theory, as the model is still far from 467 468 reaching its limits in terms of components, processes and of their nature diversity. It may then be used in 469 a more applied way, exploring other scenarios by changing initial conditions. Coupling this model with 470 other components describing the mechanisms behind these stressors would provide a relevant 471 territorialized model to anticipate trends in a context of global warming and coastline change. In a near 472 future, it would be relevant not only to improve the model realism, but also to develop analysing tools 473 already used in similar studies focusing on social-ecological systems (Mao et al. 2021, Cosme et al. 2022). 474 Indeed, with more components and processes, the computed state space may become increasingly huge 475 and difficult to interpret (Reisig 2013). A way to proceedAdditionally, it would be relevant to develop 476 methods based on model checking already in use in computer sciences (Burch et al. 1992). Another relevant 477 line to explore is to complexify our discrete and qualitative approach by using quantitative and multivalued scheme, so that we will bridge the gap with more traditional (e.g. e.g., equation-based or individual-based) 478 479 models (Vézina and Platt 1988, Kéfi et al. 2016).

481 In brief, by modeling trophic networks- with an original (EDEN) framework, we recovered observed and 482 theoretical as well as observed trajectories. With such possibilistic gualitative models, we understood its 483 dynamics and predicted new states and new trophic network TN-functioning regimes that may be observed 484 in the field. We illustrated them on a specific and well instrumented measured freshwater TN trophic 485 network. Such models provide an intuitive and robust approach to diagnose any trophic (and non-trophic) 486 network by computing all possible trajectories it may reach from a chosen initial state. The known 487 processes at play in the system help identifying all possible dynamics and thus studying the 488 contingencycounter-intuitive trajectories of such complex (social-eco-)systems. To connect such biotic 489 dynamics to human related componentsactivities would reveal even more insightful understanding of 490 complex-trophic ecosystems.

Appendices APPENDICES

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Additional Tables and Figures (Appendix 1)

493	AcknowledgementsACKNOWLEDGMENTS	
 494	We thank François-Xavier Robin for his relevant comments on an earlier draft of this paper.	
495	DATA SCRIPTS CODE AND SUPPLEMENTARY MATERIAL AVAILABILITY Data, scripts, code,	
496	and supplementary information availability	
	,	
497	Data are available in this article (Tables and Figures) (<i>citation of the data</i> Gaucherel et al, 2023);	
498	Scripts and code are available online: DOI:10.1111/2041-210X.13242 of the webpage hosting the data	
499	https://github.com/fpom/ecco (citation of the scripts and code Pommereau et al., 2022);	Code de champ modifié
500	Supplementary information is available online: XXXXDOI of the webpage hosting the data	Code de champ modifié
501 502	https://doi.org/10.5802/fake3.doi (citation of the scripts and code Gaucherel et al, 2023); [The references of the datasets, scripts and codes should also be present in the reference list and cited	Code de champ modifié
502	in the text.]	
504	CONFLICT OF INTEREST DISCLOSUREConflict of interest disclosure	
505	The authors declare that they comply with the PCI rule of having no financial conflicts of interest in	
506	relation to the content of the article. [C. Gaucherel is a recommender PCI ecology]	
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508	modeling (Project SERVICESCALES), now part of the INRAE ECODIV department.	
507		
510	References REFERENCES	
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