1	Title: Evolution of dispersal and the maintenance of fragmented metapopulations
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10	ABSTRACT:
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12	Because it affects dispersal risk and modifies competition levels, habitat fragmentation directly
13	constrains dispersal evolution. When dispersal is traded-off against competitive ability,
14	increased fragmentation is often expected to select higher dispersal. Such evolutionary effects
15	could favor the maintenance of the metapopulation by fostering spatial rescue effects. Using an
16	evolutionary model, we first investigate how dispersal evolves in a metapopulation when
17	fragmentation and aggregation of this fragmentation are fixed. Our results suggest that high
18	fragmentation indeed selects for dispersal increase, but this effect is largely reduced in
19	aggregated landscapes, to the point of being nonexistent at the highest aggregation levels.
20	Contrasted dispersal strategies coexist at high fragmentation levels and with no or low
21	aggregation. We then simulate time-varying fragmentation scenarios to investigate the
22	conditions under which evolutionary rescue of the metapopulation happens. Faster evolution of
23	dispersal favors the persistence of the metapopulation, but this effect is very reduced in
24	aggregated landscapes. Overall, our results highlight how the speed of evolution of dispersal

- and the structuration of the fragmentation will largely constrain metapopulation survival inchanging environments.
- 27
- Keywords: Dispersal evolution, fragmentation, metapopulation, evolutionary rescue, spatial
 autocorrelation
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32 INTRODUCTION

33 Dispersal, defined as the movement of individuals associated with gene flows across 34 space (Ronce, 2007), is a key process in ecology and evolution. It has important consequences 35 for population dynamics, changes in species distribution, maintenance of genetic diversity and 36 for local adaptation (Travis et al., 2013). Habitat loss and fragmentation result in decreased 37 population sizes and gene flows, which undermines population viability and ultimately species 38 survival. In landscapes that include suitable and unfavorable patches of varied size and 39 distribution, dispersal allows individuals to move between suitable patches thereby favoring the 40 survival of the metapopulation through spatial rescue effects (Levins, 1969). In a source-sink 41 context, dispersal increases spatial occupancy as source populations allow the persistence of 42 peripheral sink populations through dispersal (Pulliam, 1988). The maintenance of sink 43 populations is especially important in the context of current changes as source-sink hierarchies 44 could change in time. Given such environmental changes, dispersal helps the survival of species 45 by allowing them to follow suitable niche conditions, thereby playing a key role in range 46 expansions (Phillips et al., 2006).

47 Habitat fragmentation creates spatial heterogeneities in several ways. It decreases the 48 quantity of suitable habitat by decreasing the size and increasing the isolation of suitable 49 patches, even though it increases their number (Fahrig, 2003). In our study, fragmentation is 50 defined by the proportion of hostile vs. suitable locations (patches) and we systematically vary 51 its degree of spatial aggregation. Dispersal evolution is affected by fragmentation, due to 52 variations of different selective pressures. By definition, fragmentation increases spatial 53 heterogeneity so that dispersing propagules encounter non-suitable patches more frequently. 54 Theoretical and empirical studies suggest that such increases in dispersal costs and in spatial 55 heterogeneity select decreased dispersal (Bonte et al., 2006; Cheptou et al., 2008; Duputié & Massol, 2013; Hastings, 1983; Schtickzelle et al., 2006; Travis & Dytham, 1999). While such 56

57 a counterselection of dispersal was originally highlighted in theoretical models (Hastings, 1983; 58 Travis & Dytham, 1999), empirical evidence for such effects has accumulated in recent years, for a large variety of species, from the weed Crepis sancta (Cheptou et al., 2008), to the 59 60 butterfly Proclossiana eunomia (Schtickzelle et al., 2006) and the wolf spider Pardosa 61 monticola (Bonte et al., 2006). Habitat fragmentation however also increases inbreeding, kin 62 competition or temporal variation of the environment and all of these components usually select 63 for higher dispersal abilities (Charlesworth & Charlesworth, 1987; Cote et al., 2017; Duputié 64 & Massol, 2013; Gandon, 1999; Hamilton & May, 1977; Matthysen et al., 1995; Oldfather et 65 al., 2021; Tung et al., 2018). In addition to the modulation of overall dispersal levels, 66 fragmentation can also, under certain conditions, maintain contrasted dispersal strategies 67 simultaneously. Previous investigations suggest that such a dispersal polymorphism evolves 68 under high fragmentation and high aggregation, with dispersing and non-dispersing individuals 69 coexisting within the same population (Bonte et al., 2010). It principally appears because 70 aggregation produces a coexistence of many small patches and few large patches (Massol et al., 71 2011; Parvinen, 2002; Parvinen et al., 2020), or due to edge effects that select low dispersers at 72 the edge and high dispersers in central places (Travis & Dytham, 1999).

73 While these previous studies consider dispersal as an isolated trait, it is now widely 74 recognized that evolutionary changes in dispersal most often imply variations in phenotypic 75 traits that constrain other ecological interactions (Raffard et al., 2022). It has been highlighted 76 that when colonization abilities (here our measure of dispersal) are traded against competitive abilities, coexistence of a large number of strategies is possible along this hierarchy (Tilman, 77 78 1994). This trade-off has a long history in ecology and former studies investigated how it may 79 explain the coexistence of species within metacommunities (Calcagno et al., 2006; Tilman et al., 1997; Yu & Wilson, 2001) and how such a diversity varies when fragmentation or habitat 80 81 destruction occurs (Tilman et al., 1994, 1997). While these studies mostly focused on ecological

82 dynamics, we here use the trade-off to investigate its eco-evolutionary implications in a 83 fragmentation context. Such a trade-off could for instance occur because given a fixed quantity 84 of energy, allocation could produce a large number of small propagules (colonizer) or few large 85 propagules (competitor) (eg, Geritz et al., 1999; Smith & Fretwell, 1974). For example, the 86 weed *Crepis sancta* produces small and/or large seeds. Small seeds have high wind dispersal 87 due to their lightweight but low competitiveness due to low resource storage. In contrast, large 88 seeds have restricted dispersal due to their weight but contain more resources (Cheptou et al., 89 2008). In social insects, dispersal and reproduction could follow from the production of many 90 isolated queens that fly large distances and have high mortality or through the split of the colony 91 in a few propagules that usually disperse on short distances but may be more efficient at 92 gathering resources when founding the new colonies (Cronin et al., 2013, 2016). Habitat 93 fragmentation affects strategies along the competition-colonization trade-off in different ways. 94 First, it directly lowers the average density at the metapopulation level, thereby changing 95 competitive pressures. Second, it creates isolated patches that act as a positive filter for the best 96 dispersers. To our knowledge, only one study considers how this competition/colonization 97 trade-off affects the dispersal strategies selected by fragmentation (Tilman et al., 1994). This 98 study shows that in a spatially variable environment with an increase of fragmentation, the more 99 competitive (and thus the less dispersive) strategies disappear first, so that high dispersal 100 strategies are selected.

101 Such results are obtained without considering explicit spatial structures as the position 102 of patches is not accounted for in Tilman et al. (1994) (mean field approximation). 103 Fragmentation of the environment can however be an aggregated process, as human activities 104 such as urban development or agricultural exploitation are often concentrated in specific 105 locations. A previous work on metapopulations shows that the structuration of habitat 106 heterogeneities is crucial to study metapopulation responses to fragmentation (Hiebeler, 2000).

107 When environmental heterogeneities are spatially correlated (aggregation), predictions based 108 on mean-field approximation are often qualitatively incorrect when compared to spatially 109 explicit approaches (Hiebeler, 2000). In contrast, mean-field approximations yield correct 110 of randomly distributed fragmentation. Leaving out results in the case the 111 competition/colonization trade-off, the importance of aggregation in the evolution of dispersal 112 is highlighted by various studies (Bonte et al., 2010; Fronhofer et al., 2014; Ovaskainen et al., 113 2002; Travis & Dytham, 1999). For example, in the context of correlated extinctions, empirical 114 work on the spider mite *Tetranychus urticae* and an associated theoretical model show a 115 selection for long-distance dispersal and a decrease of local dispersal compared to spatially 116 random extinctions (Fronhofer et al., 2014). Travis and Dytham (1999) found a decrease in 117 dispersal with increased fragmentation, but an increase in dispersal with higher aggregation. 118 The risk to disperse outside of a large aggregate of suitable patches and into a hostile 119 environment is indeed lowered, so that aggregation modulates dispersal costs. Similarly, Bonte 120 et al. (2010) found a decrease of local and global dispersals with the increase of fragmentation, 121 and demonstrates that decreasing aggregation has the contrasted effect of decreasing local 122 dispersal and increasing global dispersal. To summarize, the study that considers variations of 123 dispersal strategies along a competition/colonization trade-off in fragmented habitats use a 124 spatially implicit (mean field) approach, while others use spatially explicit landscapes but 125 ignore possible competition/colonization trade-offs. The goal of our study is therefore to 126 integrate both aspects, that is to study the evolution of dispersal along the 127 competition/colonization trade-off given a spatially explicit structuration of the habitat.

Understanding this dispersal evolution has immediate consequences to better predict the maintenance of metapopulations. For instance, a selected increase in dispersal favors the exchange of individuals between patches and the colonization of empty patches (spatial rescue). Extinction may also be prevented, by the emergence of evolutionary rescue, when natural

132 selection favors adapted traits (Bell, 2017; Carlson et al., 2014; Gomulkiewicz & Holt, 1995). 133 Here, an evolutionary increase of dispersal distances could avoid a population extinction in a 134 climate change context (Boeye et al., 2012) or in a context of high mortality (Heino & Hanski, 135 2001). Given a temporally increasing fragmentation, natural selection may favor high dispersal, 136 as the availability of empty and isolated patches constantly increases. Because only highly 137 dispersive strategies can reach them, such isolated patches act as filters that favor high dispersal 138 (Heino and Hanski, 2001). Consistent with this theoretical prediction, a temporal increase of 139 fragmentation led to higher dispersal in *Drosophila melanogaster* experiments (Tung et al., 140 2018). Conversely, if evolution were to lead to less dispersal, it would potentially decrease 141 metapopulation persistence (Gyllenberg et al., 2002). The implication of the evolution of 142 dispersal for metapopulation persistence in a world that becomes increasingly fragmented is 143 therefore an important, unresolved issue.

144 Using metapopulation simulations, we studied how the spatio-temporal structuration of 145 fragmented environments acts on dispersal evolution given a competition/colonization trade-146 off. First, we fixed fragmentation and aggregation levels and investigated how dispersal 147 evolved. Second, we varied fragmentation over time to test whether dispersal evolution can 148 prevent extinction (evolutionary rescue), under various rates of evolution of dispersal. We 149 hypothesize that, in a fixed environment, higher fragmentation selects for an increase in 150 dispersal because more empty patches will become available to colonizers and inaccessible to 151 competitors. In addition, competition could be relaxed in fragmented landscapes as the average 152 occupancy is lowered. However, if the fragmentation is aggregated, large groups of suitable 153 patches could persist in the landscape. Such a situation is favorable to competitors and should 154 decrease the selection toward higher dispersal or lead to dispersal polymorphism with 155 competitors dominating aggregated patches while colonizers remain favored in isolated 156 patches. When fragmentation increases over time, we hypothesize that the occurrence of evolutionary rescue depends on the speed of evolution of dispersal, which needs to be fasterthan the speed of fragmentation to counterbalance its effects.

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160 MODEL PRESENTATION

161 Simulations and analysis were done with R 3.9. Our simulations consider a spatially explicit environment consisting of a grid of 50x50 patches wrapped into a torus to avoid edge 162 163 effects (Fig. 1). Each patch can be in one of three possible states: unsuitable, suitable and empty 164 or suitable and occupied. Only suitable and empty patches are available to dispersing 165 individuals. Importantly, we define fragmentation as the percentage of unsuitable patches. This 166 definition of fragmentation is classically considered in the literature and is directly linked to 167 other components often used to describe fragmentation such as the number of independent 168 patches, their size or their isolation (Fahrig, 2003). For a given level of fragmentation, we 169 independently vary the degree of aggregation of unsuitable patches, as controlled by the Hurst 170 coefficient. This coefficient is directly related to how similarity among patches decrease with 171 distance thereby constraining spatial autocorrelation. While we keep a simple definition of 172 fragmentation (proportion of unsuitable patches), note (1) that higher frequency of unsuitable 173 patches decreases overall connectivity; (2) that we also manipulate the effect of fragmentation 174 on local contexts by considering varying degrees of aggregation. Examples of landscapes can 175 be found in the upper left part of Fig. 1. Unsuitable patches are distributed randomly or with a 176 set percentage of aggregation (created with a fractal Brownian motion) using the NLMR and 177 *landscapetools* package (Sciaini et al., 2018). A higher aggregation means that a suitable patch 178 is more likely to be close to another one compared to the random expectation.

179 Individuals are characterized by two traits: colonization and competition capacities
180 (both integer values) directly linked through the colonization/competition trade-off. The model

relies on discrete time steps, each time step being divided in three parts: colonization,competition and extinction (see Fig. 1).

(1) Colonization. The colonization capacity defines the radius (number of patches) of the
area around the individual where its offspring are dispersed. We assume that offspring
will potentially colonize all empty but suitable patches within this range. This implicitly
assumes that individuals with larger colonization capacity are not limited by the number
of offspring they produce, assuming an increase of fecundity when dispersal distance
increases (see introduction).

189 (2) Competition. We assume that only empty suitable patches can be colonized by 190 propagules. Given that individuals fill all suitable surrounding patches with their 191 offspring, suitable empty patches are often reached by several offspring simultaneously. 192 We then assume that the competitive hierarchy favors the strategy that has the smallest 193 dispersal distance (competition-colonization trade-off, lower part of Fig. 1). The 194 surviving individual inherits the dispersal strategy of its parents, except in the case of 195 rare mutation events. When mutation occurs, the dispersal range of the mutant 196 individual is enhanced or reduced by one cell, with equal probability. Mutations incur 197 incremental variations in dispersal distance of 1, upward or downward, with equal 198 probability. Dispersal distances below 0 are not possible and discarded. Note that while 199 this situation is never observed here, a dispersal distance above 25 would mean global 200 dispersal over the whole grid. We assume that established individuals (ie, occupied 201 patches) cannot be displaced by incoming propagules, regardless of their traits.

202 (3) Extinction. We assume that extinction probability does not depend on the dispersal trait. 203 Occupied suitable patches therefore become empty (but still suitable) with a fixed 204 probability e at each time step (e=0.05).

Each landscape is populated, at the beginning of the simulation, with ten populations that are randomly distributed on suitable patches. These populations are assumed to be highly dispersive (colonization capacity of twelve). We verified that initial conditions (number of populations and initial colonization capacity) do not affect the equilibrium outcome (Supplementary information Figure 1).

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Scenario 1: Evolution of dispersal in fixed fragmented landscapes

212 In the first scenario, we fix the landscape and study how dispersal evolution depends on 213 the levels of fragmentation and aggregation. Fragmentation corresponds to a specified 214 percentage of unsuitable patches (i.e. 0, 20, 40, 60, 80, 90, 95 or 99% of patches are assumed 215 unsuitable). These unsuitable patches are aggregated at varying degrees (0, 20, 40, 60, or 80%). 216 To assess repeatability, twenty different landscapes are generated for each combination of 217 fragmentation and aggregation. The mutation rate is set at 0.1. Each simulation lasts 50 000-218 time steps. Because simulations are stochastic, they never reach a completely stable 219 equilibrium, but we visually checked for each simulation that 50 000 time steps allowed the 220 system to reach a stable regime that can be characterized (Figure S2). It means that the mean 221 and the variance stay stable over at least 5 000 time steps (more discussion is provided in 222 supplementary information S2). We record the mean dispersal capacities of individuals during 223 the simulation and the occupancy of each dispersal strategy.

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Scenario 2: Evolutionary rescue under progressively increasing fragmentation

In the second scenario, we progressively increase the level of fragmentation over time. We systematically manipulate the rates of fragmentation and of mutation to investigate conditions under which dispersal evolution can delay extinction. The grid is supposed to be fully suitable at the onset of the simulation and for the first 200-time steps. We then 230 progressively increase fragmentation until the metapopulation becomes extinct. As in the first 231 scenario, the increase in fragmentation occurs with random or aggregated distributions of 232 unsuitable patches (levels of aggregation: 0%, 10%, 20%, 40%, 60%, 80%). Rates of 233 fragmentation correspond to the probability that a suitable patch becomes unsuitable within a 234 given time step. We tested three rates of fragmentation (0.0001, 0.001, 0.01). As evolutionary 235 rescue is construed as a race between the speed of the disturbance and the speed of adaptation 236 (Gomulkiewicz & Holt, 1995), we also systematically manipulate the speed of evolution by 237 considering different rates of mutation (0.001, 0.01, 0.1). We replicate each combination of 238 aggregation, fragmentation rate and mutation rate forty times. We record the fragmentation at 239 population extinction as an index of the resistance of the metapopulation to the disturbance. 240 Higher values of this index show that evolution of dispersal allowed the metapopulation to 241 survive higher levels of the disturbance. Evolutionary rescue occurs if metapopulations with 242 evolution of dispersal resist higher disturbance levels than metapopulations without dispersal 243 evolution. For each set of simulations, we also record the variations of dispersal strategies 244 (occupancy of the various dispersal phenotypes) over time to identify the path that evolutionary 245 rescue takes.

246

247 **RESULTS**

248 Evolution of dispersal in fixed fragmented landscapes

Higher fragmentation selects for increasing mean dispersal distances. In nonfragmented landscapes, competitive strategies eventually dominate so that dispersal distance quickly evolves close to one (Fig. 2a and b). Such a strategy remains dominant for all low levels of fragmentation (0 to 60%). High dispersal is selected under higher fragmentation, especially strongly when fragmentation is random (7.27 ± 1.08 patches at 99%, red line in Fig. 2a, see also Fig. 2c). However, adding aggregation strongly decreases this selection effect. For instance, a little bit of aggregation (20%, orange line in Fig. 2a, see also Fig. 2d) suffices to lower the selected dispersal distance in very fragmented landscapes to 2.09±1.02 patches. Higher aggregation (40 to 80%) further decreases the selected dispersal distance, so that fragmentation hardly has any effect on selected dispersal when aggregation is high (blue lines, Fig. 2a). Aggregation therefore qualitatively changes the results of mean field models (such as Tilman et al., 1994).

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Evolution of polymorphism in fragmented landscapes.

262 Beyond the observed variations in mean dispersal distances, the long-term variability of 263 dispersal strategies also depends on fragmentation and aggregation. Particularly, when 264 fragmentation is sufficient, we observe the coexistence of several dispersal strategies 265 (polymorphism, Fig. 3). In all cases of polymorphisms, we observe similar patterns. Suitable 266 patches that are close to one another sustain the less dispersive strategies, while isolated patches 267 act as filters that favor the more dispersive strategies. The set of polymorphic strategies however 268 vary depending on the relative positions of patches. For instance, given a very high 269 fragmentation (99%) with no or little aggregation (20% or less), few suitable patches are close 270 to one another by chance (purple patches, Fig. 3b). Because the distances among these patches 271 is still quite important, the dispersal strategy they sustain is still quite high (around 5). Other 272 patches are more isolated (blue patches, Fig. 3c) and act as a selective pressure favoring very 273 high dispersal distances (around 9). When fragmentation is slightly lower (80 to 95%) and 274 aggregation slightly higher (20 to 40%), large aggregates of suitable patches occur in the 275 landscape (red patches, Fig. 3e) and favor competitive strategies (dispersal distance around 1). 276 The remaining suitable patches are isolated and favor a continuum of more dispersive strategies.

277

Evolutionary rescue under progressively increasing fragmentation

278 When fragmentation increases over time, fast dispersal evolution allows a longer 279 persistence of the metapopulation, i.e. an evolutionary rescue. Fig. 4 shows this evolutionary 280 rescue as the difference (orange arrows) between the scenario with no evolution (mutation rate 281 equal zero) and the three scenarios with more or less rapid evolution. Intuitively, evolutionary 282 rescue occurs and is strongest when there is no aggregation, fragmentation rate is low, and 283 mutation rate is high (mean difference of 3.04% between scenarios without and with evolution, 284 Fig. 4a). Evolutionary rescue is largely decreased when fragmentation rate is higher (a 285 difference of 0.63%, Fig. 4c). Variations in the potential of evolutionary rescue are not 286 continuous. Rather, a jump in the extinction time when mutation rates increase can be identified. 287 This jump is relative to the fragmentation rate. Under our set of parameter values, evolutionary 288 rescue occurs when the mutation rate is ten times higher than the fragmentation rate (Fig. 4a,b,c, 289 blue arrows). Finally, we stress that aggregation largely constrains evolutionary rescue. No 290 potential for evolutionary rescue can be identified in aggregated landscapes (Fig. 4d,e,f).

291

292 **DISCUSSION**

293 Our study shows an increase of dispersal capacities in fragmented landscapes in the context of competition/colonization trade-offs. Aggregation acts as an opposite force, as 294 295 decreased dispersal is selected in more aggregated landscapes. At high fragmentation and low 296 aggregation, different strategies can be selected and can coexist, with better competitors in 297 aggregated patches and better colonizers in isolated patches. Such an evolution of 298 polymorphism allows a good global coverage of available space. When fragmentation increases 299 with time, the rapid evolution of dispersal facilitates the survival of the metapopulation but this 300 evolutionary rescue effect can only be observed in non-aggregated landscapes and when 301 fragmentation rate is not too high.

302 The selection of more dispersive strategies in fragmented landscapes in a context of 303 competition/colonization trade-offs is congruent with Tilman et al. (1994) which also relies on 304 this trade-off. Other studies on the evolution of dispersal in spatially heterogeneous systems, 305 but in the absence of a competition/colonization trade-off, show a reverse pattern, as dispersal 306 is then counter selected because dispersal costs are enhanced by spatial heterogeneities 307 (Hastings, 1983; Travis & Dytham, 1999). This highlights that patterns of selection strongly 308 depend on the trade-off structure associated with dispersal traits. Recent works highlight the 309 importance of dispersal syndromes (Raffard et al., 2022; Stevens et al., 2014), i.e. the fact that 310 dispersal traits may be directly coupled to traits defining ecological interactions. The 311 competition/colonization trade-off falls within this category, as variations of dispersal are 312 directly coupled to competition hierarchies. Our results therefore highlight how such a 313 syndrome could lead, for some landscapes, to the selection of higher dispersal, while works that 314 consider evolution of dispersal alone (eg, Hastings, 1983; Travis and Dytham, 1999) would 315 produce the reverse pattern. Application of either framework of course depends on the types of 316 organisms that are considered and whether dispersal traits are competitively costly.

317 In particular, our model assumes that the fecundity of the organism under consideration, 318 i.e. the number of offspring produced, increases with increasing dispersal distance. This 319 provides an additional advantage for dispersive strategies that will produce many more offspring and therefore occupy space more quickly if there is no superior competitor present. 320 321 Many previous models do not make this assumption and use constant fecundity (eg, Bonte et 322 al., 2010; Travis and Dytham, 1999). This hypothesis may influence our results in several ways. 323 With constant fecundity, selection of dispersive strategies is likely reduced, leading to a smaller 324 mean dispersal in highly fragmented habitats, lower abundances in the landscape, and early 325 extinctions. Dispersal polymorphism should stay present because isolated patches can only be 326 reached by dispersive strategies. However, this assumption of increasing fecundity with 327 increasing dispersal distance is not biologically irrelevant and can be linked to various groups 328 of organisms. A certain amount of energy could be allocated in either a few large, poorly 329 dispersing offspring or in many small, highly dispersing offspring. This rationale has been 330 largely used in the context of variations of plant seed size (eg, Henery & Westoby, 2001; 331 Muller-Landau et al., 2008). It could also apply in the context of social insect colonies. For 332 instance, in ants with the production of large propagules consisting of a queen and workers that 333 disperse over short distances or small propagules of a single queens dispersing over long 334 distances (Cronin et al., 2013).

335 We explain the selection of higher dispersal in fragmented landscapes by two 336 mechanisms. First, fragmentation decreases overall occupancy (on the entire grid). Thereby, 337 when a patch is emptied, the number of possible colonizers (ie, of suitable filled patches) is 338 reduced. This reduces the average competition level. The advantage of competitive strategies 339 is therefore reduced. Second, fragmentation intensifies the strength of the competition for space 340 which favors colonizers. Isolated patches in fragmented landscapes can only be exploited by 341 highly dispersive strategies. Effects of fragmentation on mean levels of dispersal have led to 342 contrasted results in empirical studies (Cheptou et al., 2017). Our results of a selection of higher 343 dispersal is for instance coherent with empirical studies of nuthatches (Sitta europaea) in 344 Belgium (Matthysen et al., 1995). Similarly, metapopulation study of the Glanville fritillary in 345 Finland shows that isolated patches of the metapopulation act as positive filters for the more 346 dispersive strategies (Hanski et al., 2004) and that this variation can be linked to allelic 347 variations constraining flight metabolism (Haag et al., 2005). Conversely, a decrease of 348 dispersal at higher fragmentation levels has been observed in various animal or plant species 349 (Bonte et al., 2006; Cheptou et al., 2008; Schtickzelle et al., 2006). Spatial heterogeneity and 350 competition decrease are two forces that act with opposite effects, the former decreasing 351 dispersal (higher dispersal cost) while the latter increases it (decreased abundancies in

352 fragmented landscapes, relax competition). The importance of each force varies among species353 and needs to be systematically considered to better predict changes in dispersal.

354 We found that aggregation largely reduces the selection of dispersal strategies, to the 355 extent that such a selection cannot even be detected when aggregation is larger than 40%. This 356 points out the importance of spatially explicit models. In a previous work, Hiebeler (2000) 357 showed how mean field approximations provide accurate occupancy predictions for random 358 fragmented landscapes, but not when aggregation exists. Similarly, we show here that while 359 our results on dispersal evolution in random landscapes are coherent with mean field 360 approximations (Tilman et al., 1994), such approximations do not provide qualitatively 361 adequate variations when aggregation takes place. We explain the reduction of dispersal due to 362 aggregation by the fact that it favors the replacement of colonizers by competitors because of a 363 high probability to find a favorable patch next to another favorable patch. The landscape is there 364 continuous, so that competition is selected in such localities. Such a result is in line with Bonte 365 et al. (2010) who found an increase of local dispersal (our competitive strategy) and a decrease 366 of long-distance dispersal (our colonizer strategy) in aggregated fragmentation scenarios. We 367 therefore completely agree with the necessity of spatially explicit approaches to better 368 understand the dynamics of fragmented metapopulations (Hiebeler, 2000). Here, a simple 369 mean-field approach would yield an overestimation of dispersal evolution and of associated 370 evolutionary rescue effects.

Our model is based on mutations and on the selection of certain phenotypes resulting from these mutations. While our results can be largely interpreted from a selection point of view, we explicitly account for stochastic components, both in the mutation process and in the random patch extinction process. This latter source of stochasticity leads to genetic drift in our simulations. Effects of drift are particularly visible for small metapopulation sizes (ie, on the brink of extinction), and indeed we observed broader distributions of phenotypic values in such 377 conditions. To assess the importance of these stochastic components, we undertook 20
378 replications of each parameter combination in scenario one and 40 in scenario two. The
379 consistent qualitative variations of dispersal distances however suggest a large role of selective
380 processes.

381 We observe dispersal polymorphism when fragmentation is high and aggregation low 382 to intermediate. Such landscapes contain a mix of large aggregates of patches and of isolated 383 patches. The strategy favored in the aggregates of patches is more competitive, and the dispersal 384 distance selected there depends on how loose the aggregates are. When aggregation produces 385 continuous aggregates, the most competitive strategies are favored (dispersal distance close to 386 1, Fig. 3f), while when aggregates are looser, selected dispersal distances could be higher (Fig. 387 3f). In all cases, isolated patches favor more dispersive strategies. These results are coherent 388 with previous theoretical studies that show how fragmentation can favor dispersal 389 polymorphism. In particular, some of them showed that polymorphism is prevalent when few 390 large patches (our patch aggregates) co-occur with small patches (our isolated patches) (Bonte 391 et al., 2010; Massol et al., 2011; Parvinen, 2002; Parvinen et al., 2020). A large literature exists 392 on how ecological dynamics of metapopulations under fragmentation leads to changes in 393 persistence and to variations in diversity (Bascompte & Rodriguez, 2001; Bascompte & Solé, 394 1996; Ovaskainen et al., 2002; Solé et al., 2004). Previous works highlight the critical role of 395 patchiness (Bascompte and Rodriguez, 2001) or of extinction thresholds (Bascompte and Solé, 396 1996). Here, our goal is rather to assess how fragmentation affects the evolution of dispersal 397 and its eco-evolutionary consequences for the metapopulation dynamics. Such an evolution 398 may in turn affect persistence (and diversity) when it fosters evolutionary rescue.

Evolutionary rescue can be construed as a race between speed of adaptation and of environmental deterioration. Hence, the faster the evolution and the slower the perturbation, the more likely the rescue. We observe that such expectations are met when fragmentation is 402 random (no aggregation). Dispersal evolution delays the extinction of the population when 403 fragmentation rate is low and mutation rate high. Fast selection of good dispersers then occurs. 404 As these are adapted to occupy isolated patches, such strategies foster spatial rescue in the 405 highly fragmented landscapes. Slow evolution would not allow that. At the onset of 406 fragmentation, the grid is continuous, and mostly occupied by competitors. If fragmentation is 407 too fast, there is no time for dispersers to appear and become selected and to fill isolated patches. 408 Interestingly, our study shows that rescue happens as a jump phenomenon, being only possible 409 when mutation rates are higher (10 times higher in our model) than perturbation rates. No 410 evolutionary rescue occurs when fragmentation is aggregated. Aggregation delays extinction 411 by itself even without evolution. Under high fragmentation and aggregation levels, suitable 412 patches make small continuous groups that facilitate the local persistence of competitors. In an 413 aggregated context, dispersal evolution is absent or strongly constrained (blue curves on Fig. 414 2a) so that little evolutionary potential exists. In the absence of such an adaptive potential, evolutionary rescue cannot act. Our results on the possibility of rescue through evolutionary 415 416 changes of dispersal agree with former theoretical works where fragmentation either stemmed 417 from climatic changes (Boeye et al., 2012) or from heterogeneities in mortality (Heino & 418 Hanski, 2001). While in the actual context of fast environmental changes, it may seem 419 complicated for species to evolve quickly enough (10 times faster than the perturbation), several 420 examples of fast evolution of dispersal in fragmented systems have been reported (reviewed in 421 Cheptou et al., 2017). Whether such evolution are sufficient to affect long term metapopulation 422 persistence is however unknown. The fact that evolutionary rescue does not happen here in 423 aggregated landscapes also has important implications. The current fragmentation of habitats is 424 a complex non-random process that may be frequently auto-correlated in space, therefore 425 producing aggregated structures. For instance, the construction of additional urban areas next 426 to existing urban areas creates aggregated landscapes. Studies from the Tabriz Metropolitan 427 Area (Iran) show that the destruction of suitable habitats surrounding the cities result in the 428 creation of aggregated non-suitable patches (Dadashpoor et al., 2019b, 2019a). Aggregation of 429 fragmentation can also be linked to the displacement and development of agricultural activities. 430 In Beijing City, China, landscape patterns show important and complicated changes in the 431 distribution of urban and agricultural lands. Economic development expands cultivated land 432 and construction into forests and grasslands resulting in aggregated and less diverse landscapes 433 (Li et al., 2017). We propose that when fragmentation happens in such aggregated ways, 434 evolution will likely play a minor role in the maintenance of the metapopulation.

435 Our study highlights the importance of considering dispersal syndromes (here through 436 the competition/colonization trade-off) and the structuration of habitat fragmentation to better 437 understand how dispersal evolves in disturbed landscapes. We acknowledge that our model is 438 quite simple and can only be used to provide baseline scenarios. For instance, fragmentation 439 can create changes not only in competition intensity, but also in other community aspects (eg, 440 presence of mutualists and enemies, see Cheptou et al., 2017). While we simply focus on the 441 colonization-competition trade-off, evolutionary changes can also involve other phenotypic 442 traits. Colonization of empty patches, usually free of conspecifics, could for instance lead to 443 the fast evolution of intrinsic growth rates (Williams et al., 2019). We hope that the results we 444 present here will motivate efforts to better understand the multidimensionality of dispersal 445 evolution and its implications for the future of biodiversity.

446

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449 DATA AVAIBILITY

- 450 Model and analysis scripts are available on github:
- 451 <u>https://github.com/bfinand/Model_dispersal_evolution</u>
- 452

453 **CONFLICT OF INTEREST**

- 454 The authors declare no conflict of interest.
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622 FIGURES

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626 Figure 1: Illustration of a simulation based on the competition/colonization tradeoff in a fixed 627 environment scenario. Upper panels detail the various parts of a given timestep, while the box below shows the competition/colonization process when two individuals arrive on the same 628 629 patch. For each time-step, individuals colonize all suitable and empty patches within their 630 dispersal distance. Individuals mutate with a small probability. If a mutation occurs, the dispersal distance of the individual is modified by 1, upward or downward with equal 631 632 probability. Extinction events follow, with a probability e. If two (or more) individuals arrive 633 on the same patch, the one with the smallest dispersal distance, being competitively dominant, 634 wins the patch. One simulation lasts 50 000 time-steps.

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Figure 2: Dispersal (mean +/- SD) at the end of simulations (at equilibrium) depending on environment fragmentation and aggregation (a), and over time (b-d) for the 20 replicates for conditions of no fragmentation and no aggregation (b), 99% of fragmentation and no aggregation (c) or 99% of fragmentation and 20% of aggregation (d). Note that higher dispersal distance is selected in random fragmented landscapes, but that aggregation of fragmentation lowers this selective effect. Shadows around curves represent SD.

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649 Figure 3: 2 examples of simulations showing dispersal polymorphism. (a) and (d) show the 650 presence of dispersal strategies over time in two separate simulations. (b) and (e) represent the grid at the end of the corresponding simulations. (c) and (f) show the relative abundance of each 651 652 strategy (mean percentage +/- SD) over the last 5 000-time steps. For (a) and (d) the intensity 653 of black represents the proportion of each strategy for the given time. It is log-transformed for 654 (d). For (b) and (e) grey patches are unsuitable, white patches are suitable and empty, and 655 coloured patches are suitable and occupied by populations differing in dispersal strategies 656 (ranging from low dispersal in red to high dispersal in blue). Dispersal strategies are similarly 657 color coded in panels (c) and (f). The first row of panels (a-c) shows an example with two 658 equally abundant dispersal distance strategies (dispersing at 5 and 9 patches). Conditions are fragmentation of 99% and no aggregation. The second row of panels (d-f) shows an example 659 where one dispersal distance strategy (at 1.1 patches) dominates (fragmentation of 95% and 660 661 aggregation of 20%).

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Figure 4: Fragmentation level leading to the metapopulation extinction versus mutation rate for different scenarios of fragmentation rate and aggregation. Orange arrows highlight the difference of extinction thresholds between no evolution and fast evolution, a proxy for maximal evolutionary rescue. Blue arrows highlight the change in mutation rate that has a maximal effect on evolutionary rescue. Note that this occurs when mutation rates become roughly ten times higher than fragmentation rates (a-c). Evolutionary rescue is largely decreased in aggregated landscapes (d-f).

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